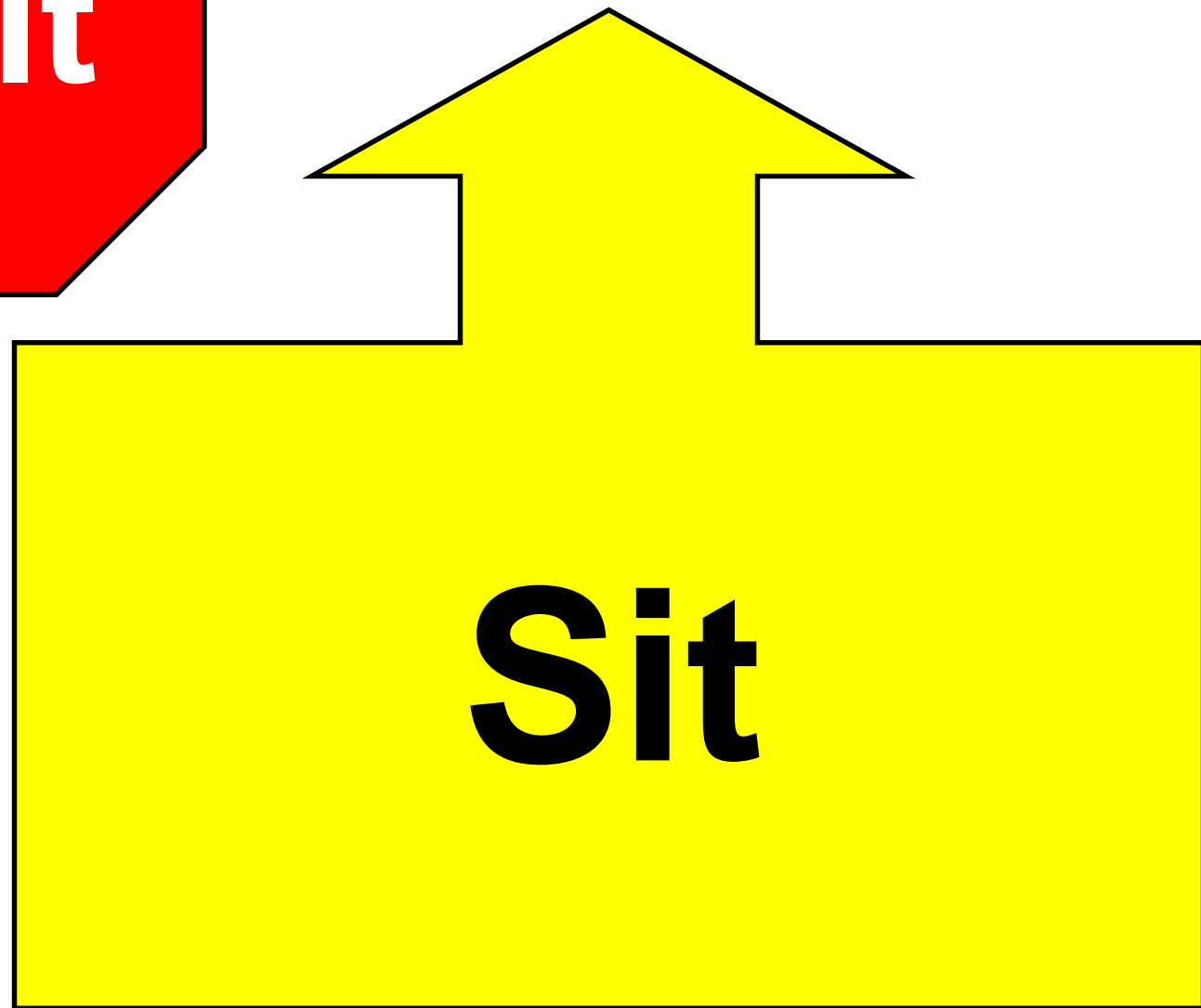


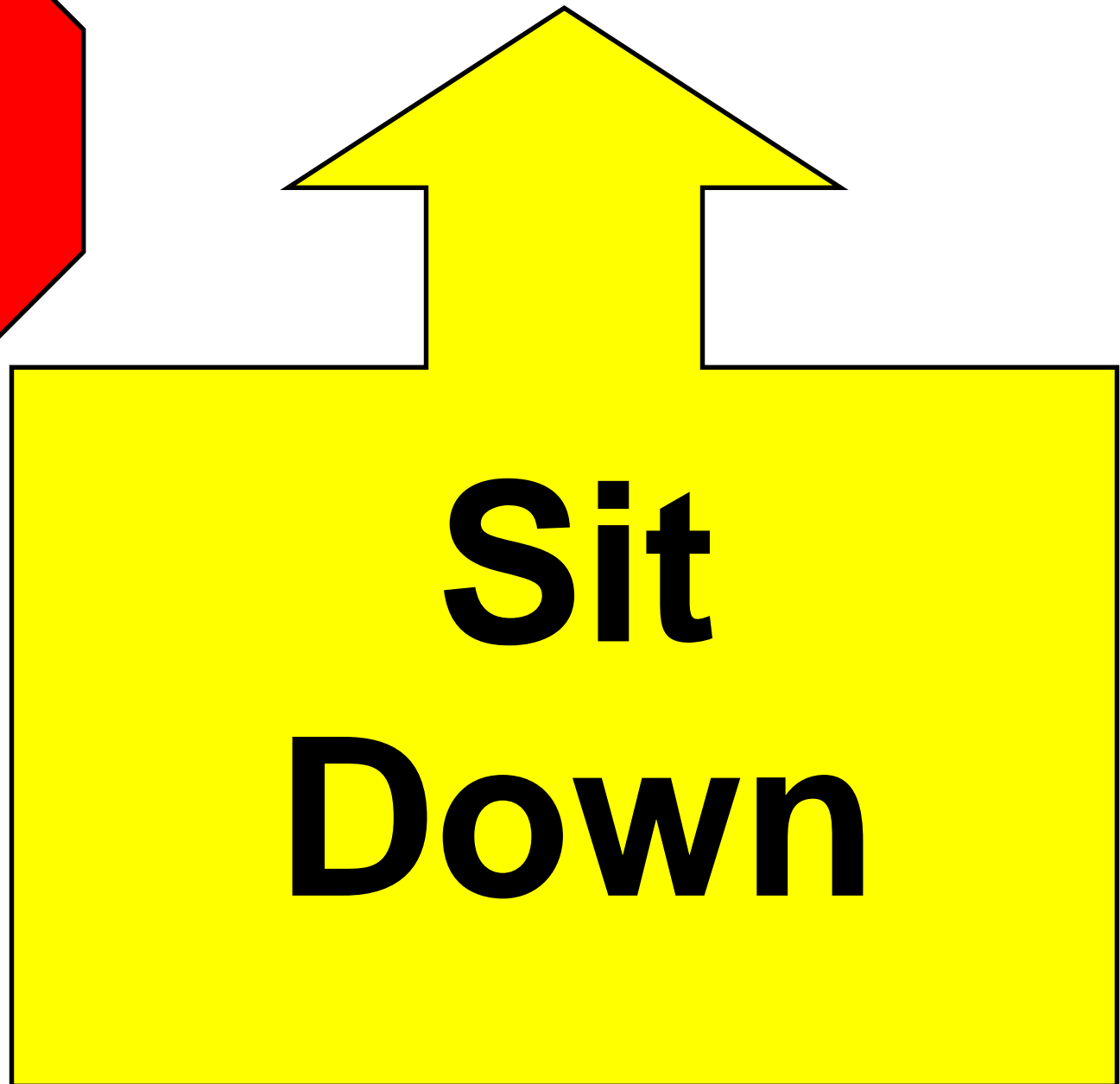


Start

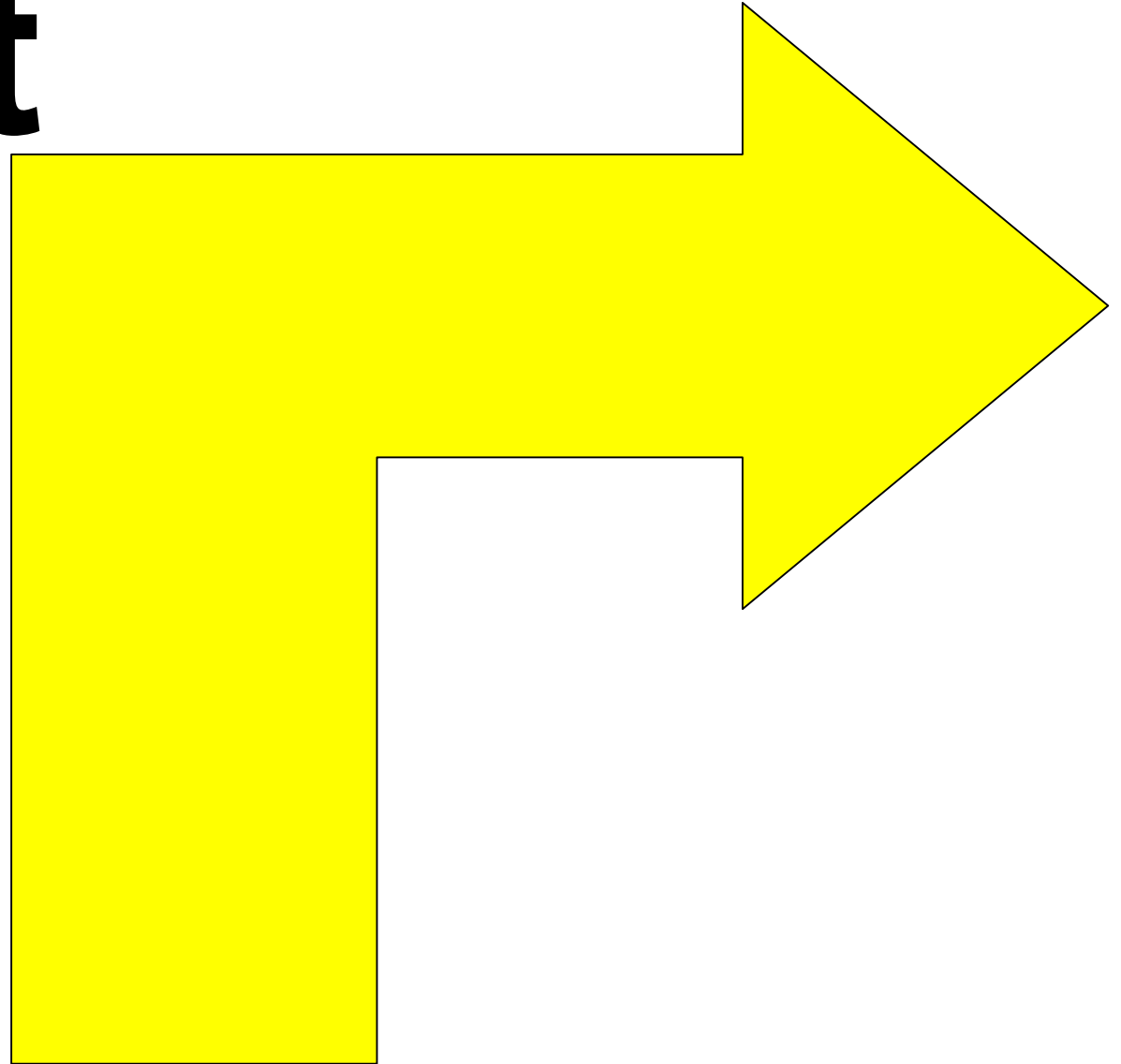


FINISH

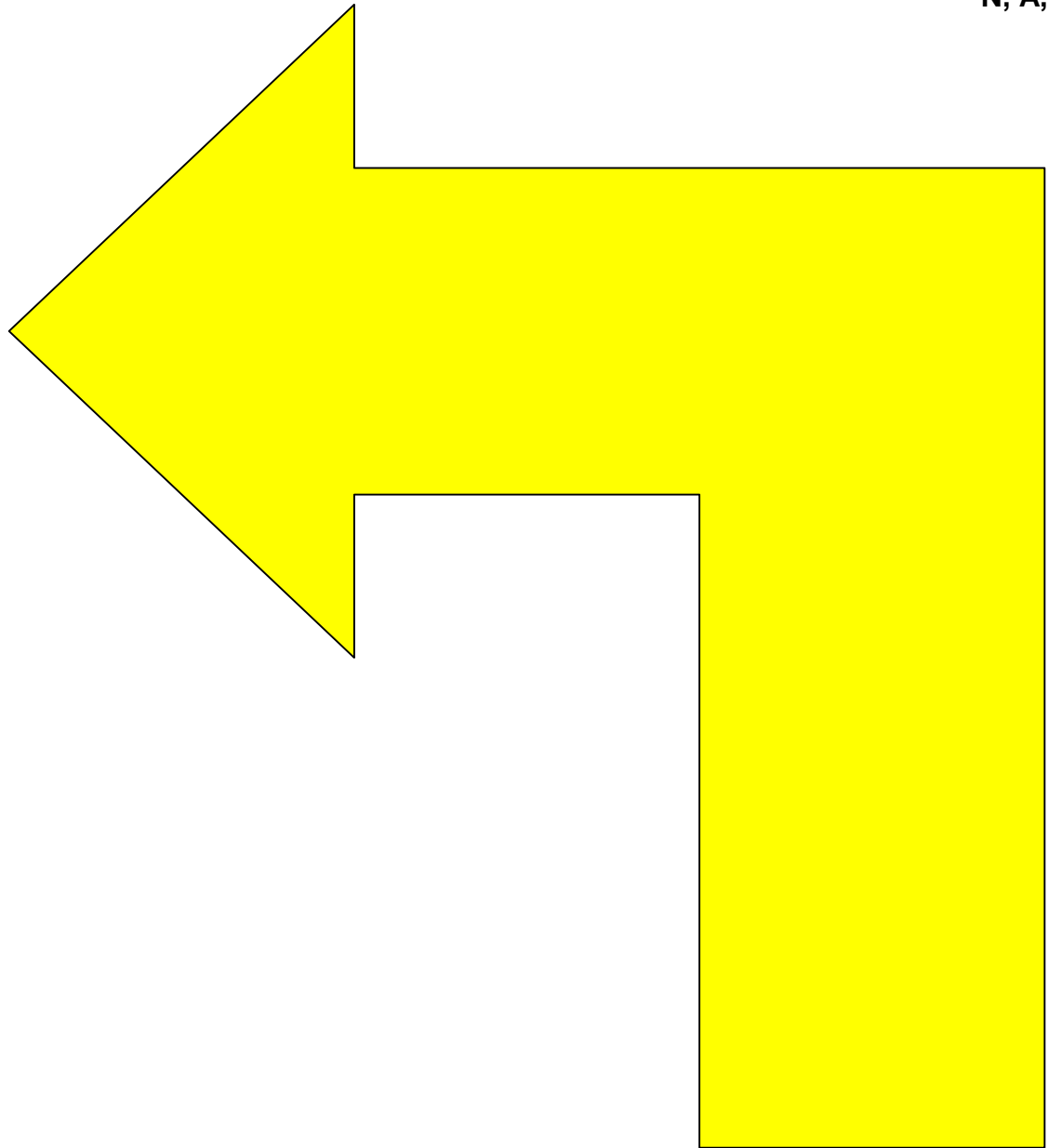




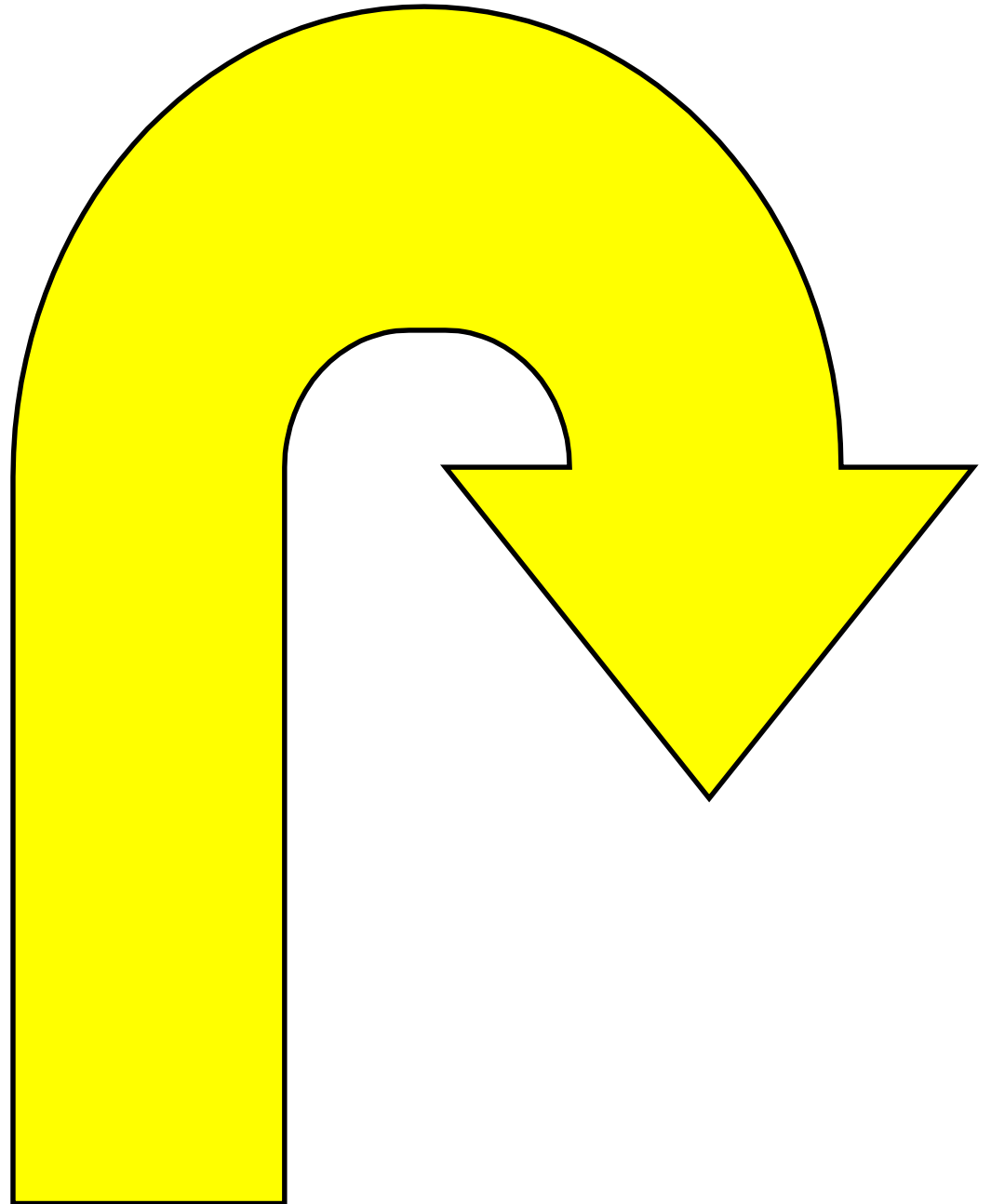
**Right
Turn**



**Left
Turn**



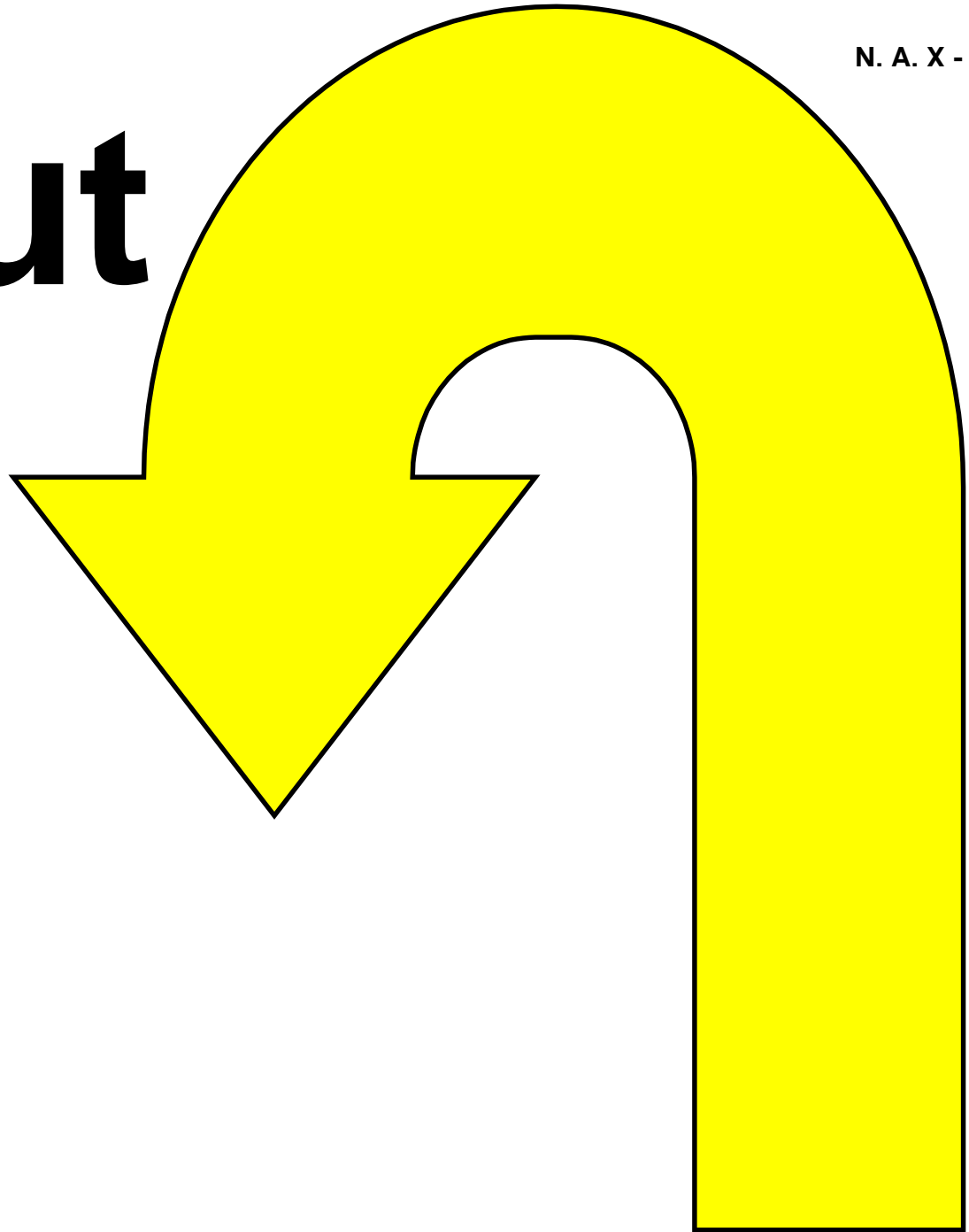
**About
Turn
Right**



About

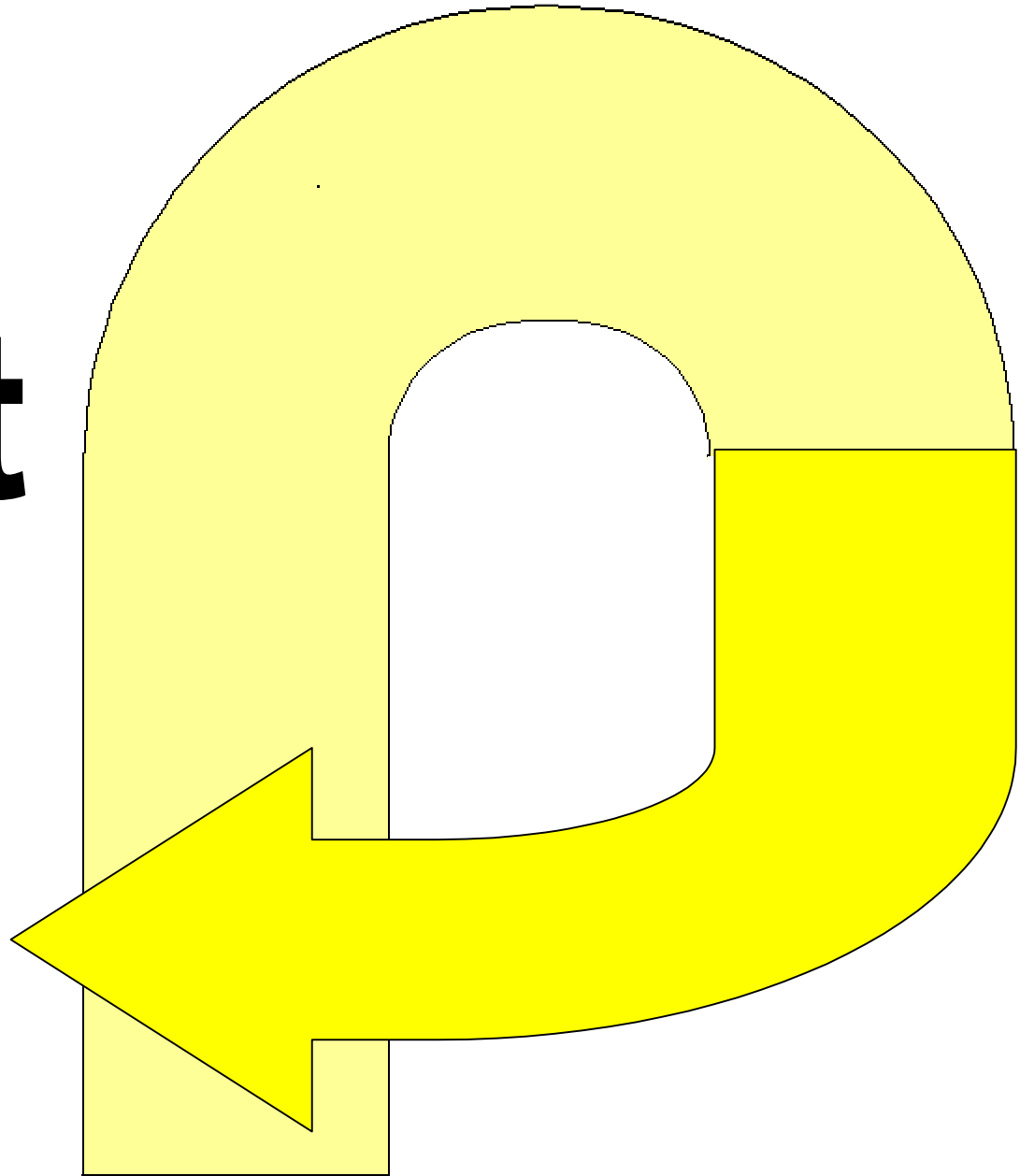
“U”

Turn



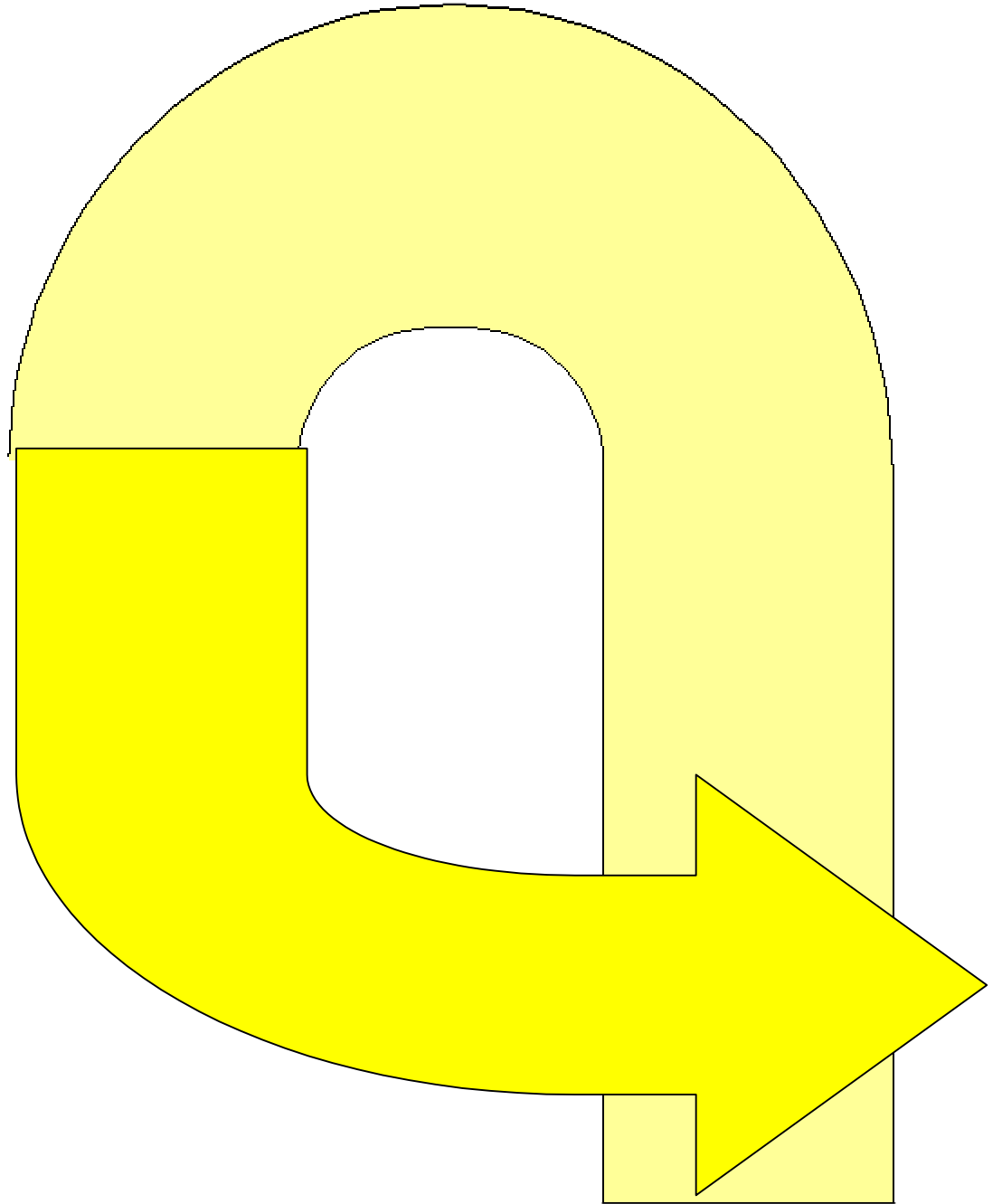
270°

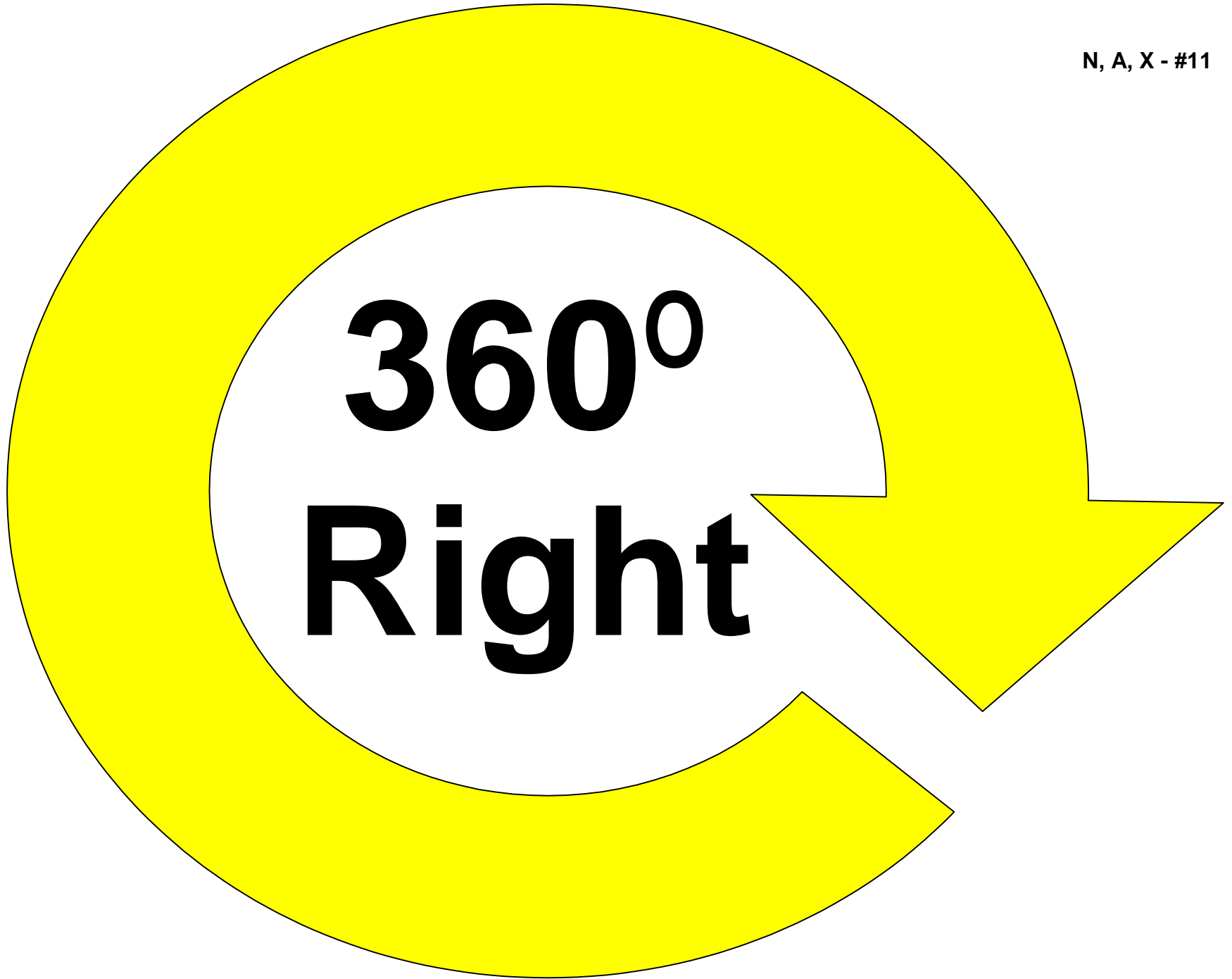
Right



270°

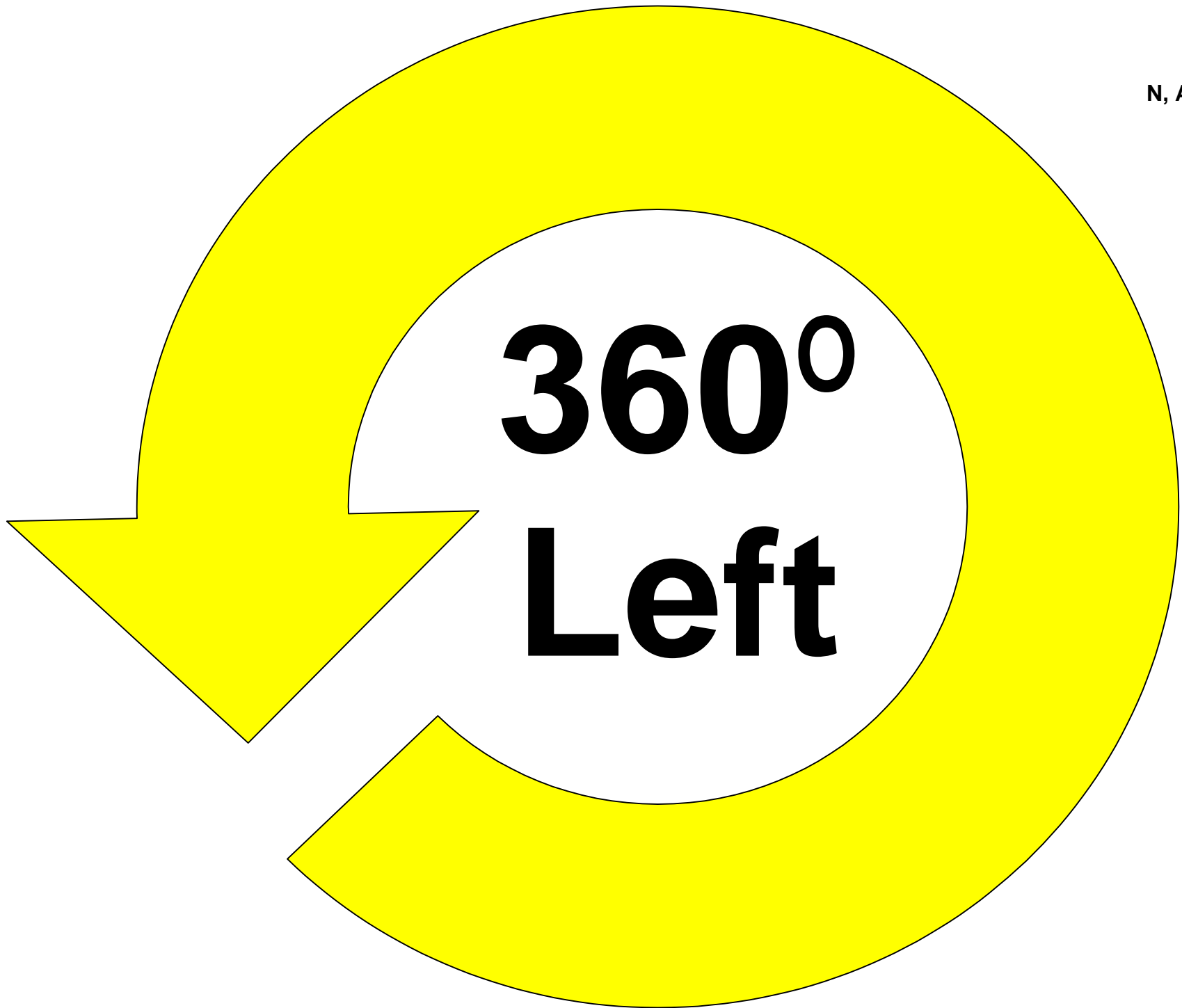
Left





360°

Right





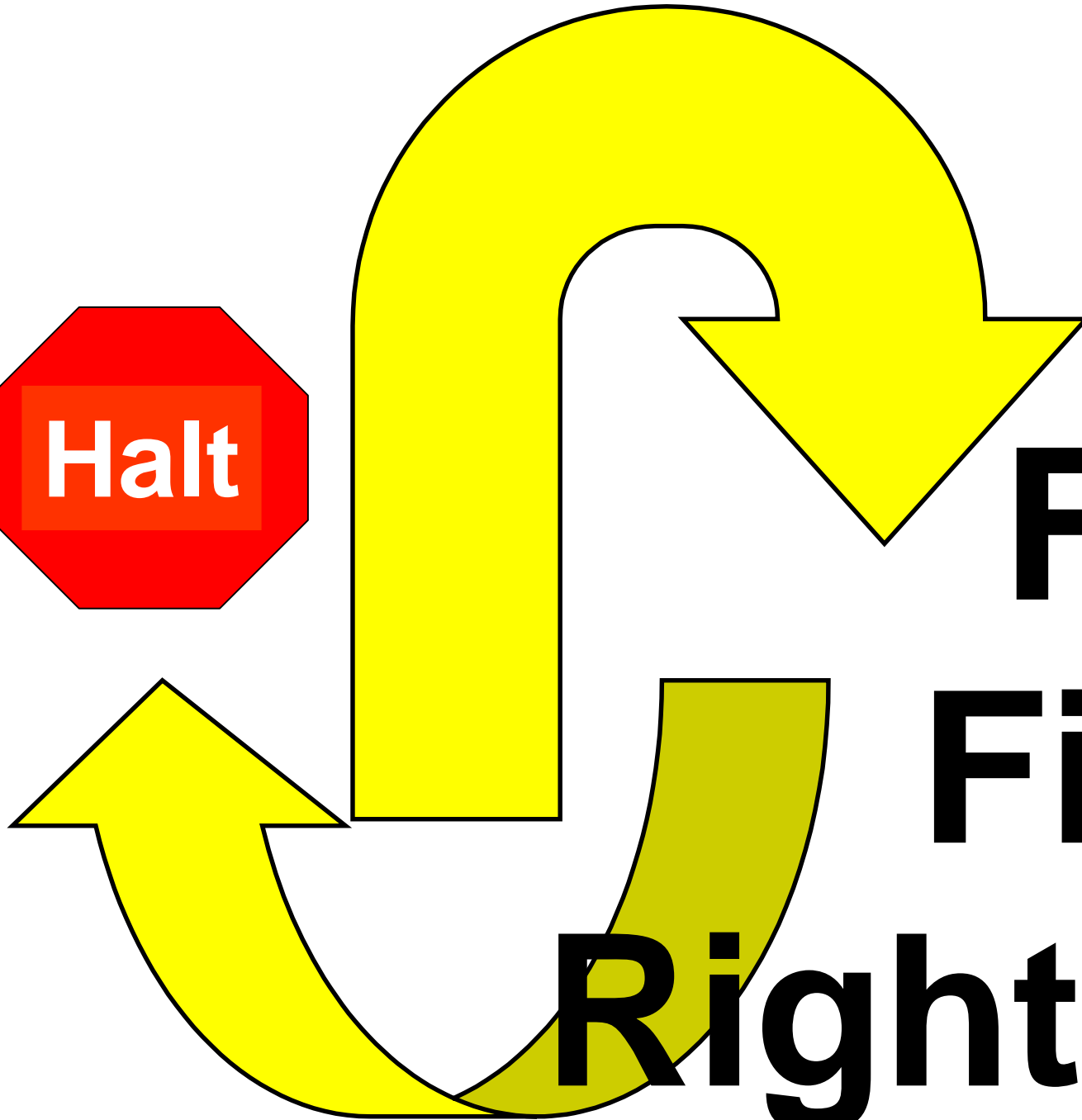
Call

Front

Finish Right

Forward





Call

Front

Finish

Right Halt





**Slow
Pace**

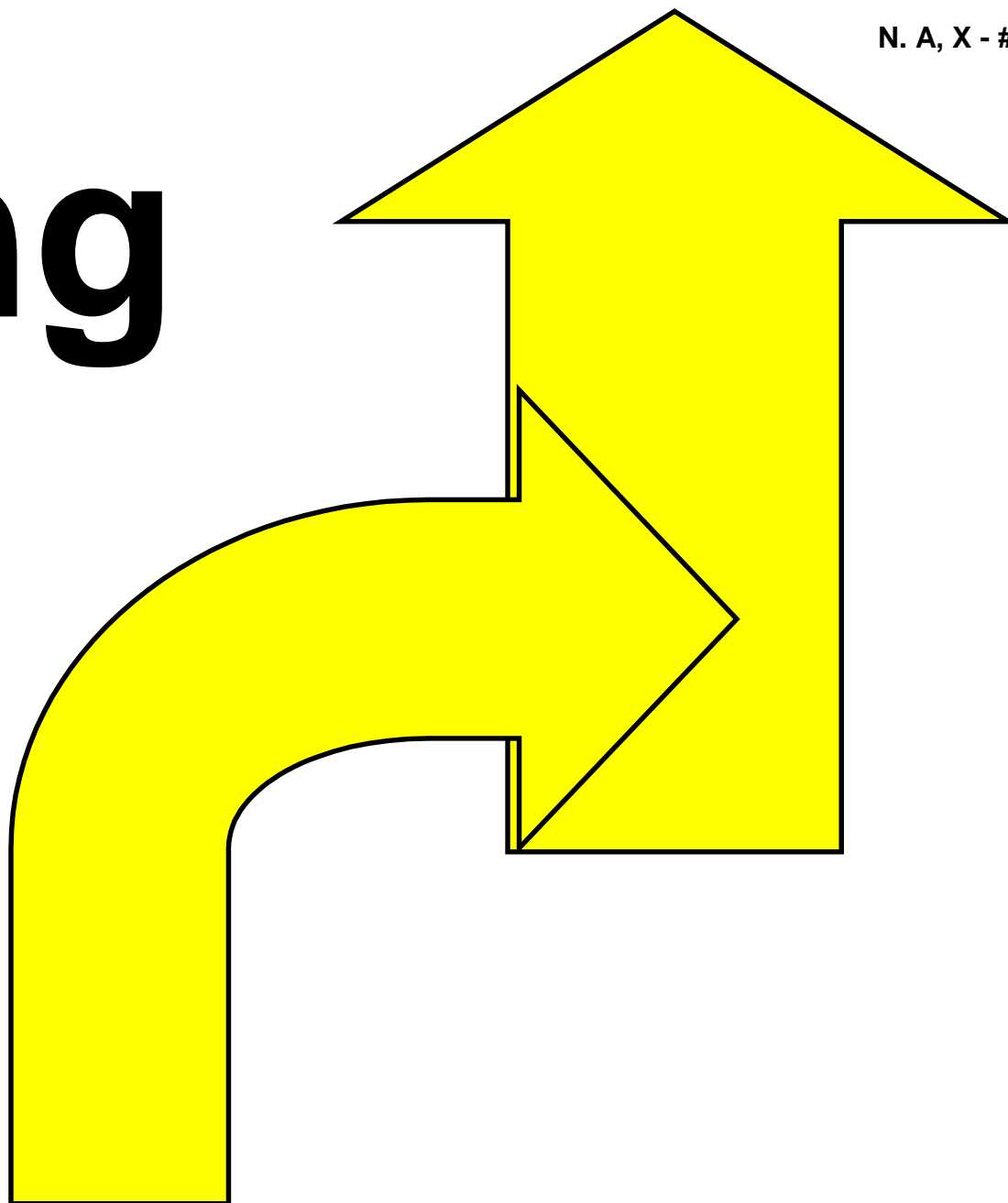


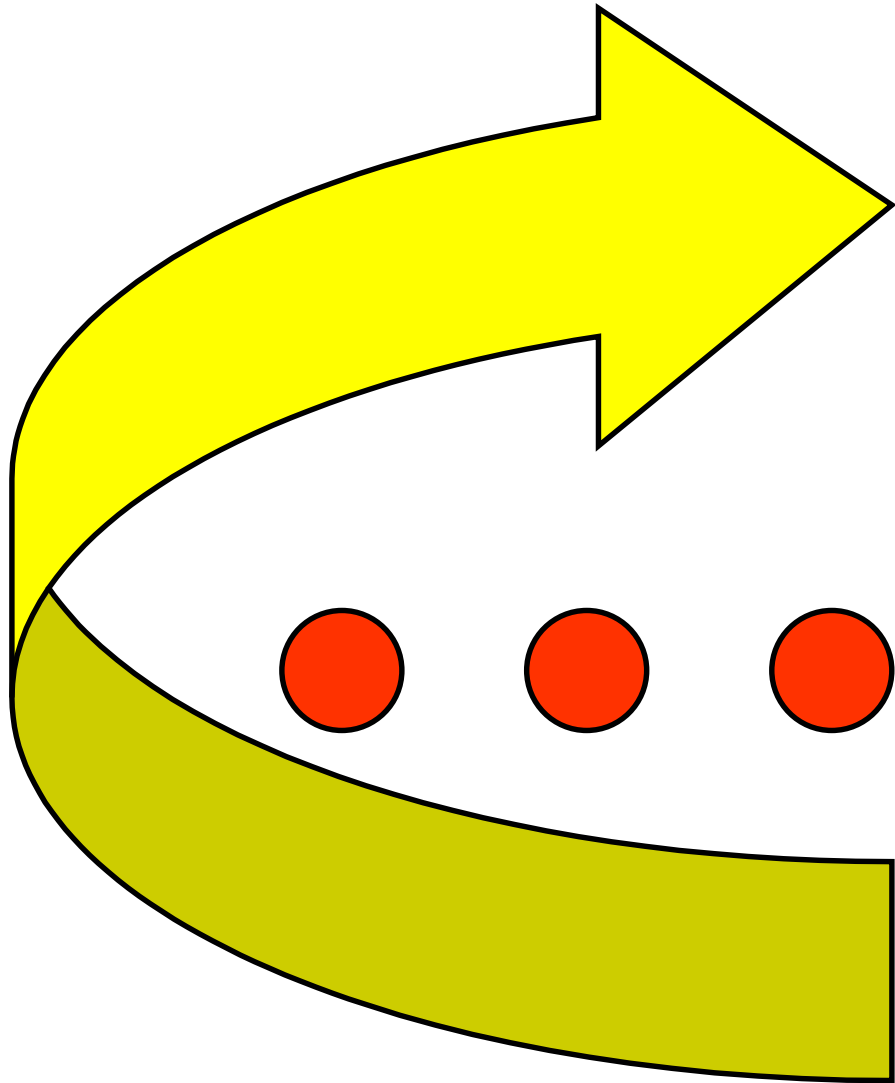
**Fast
Pace**



**Normal
Pace**

Moving
Side
Step
Right

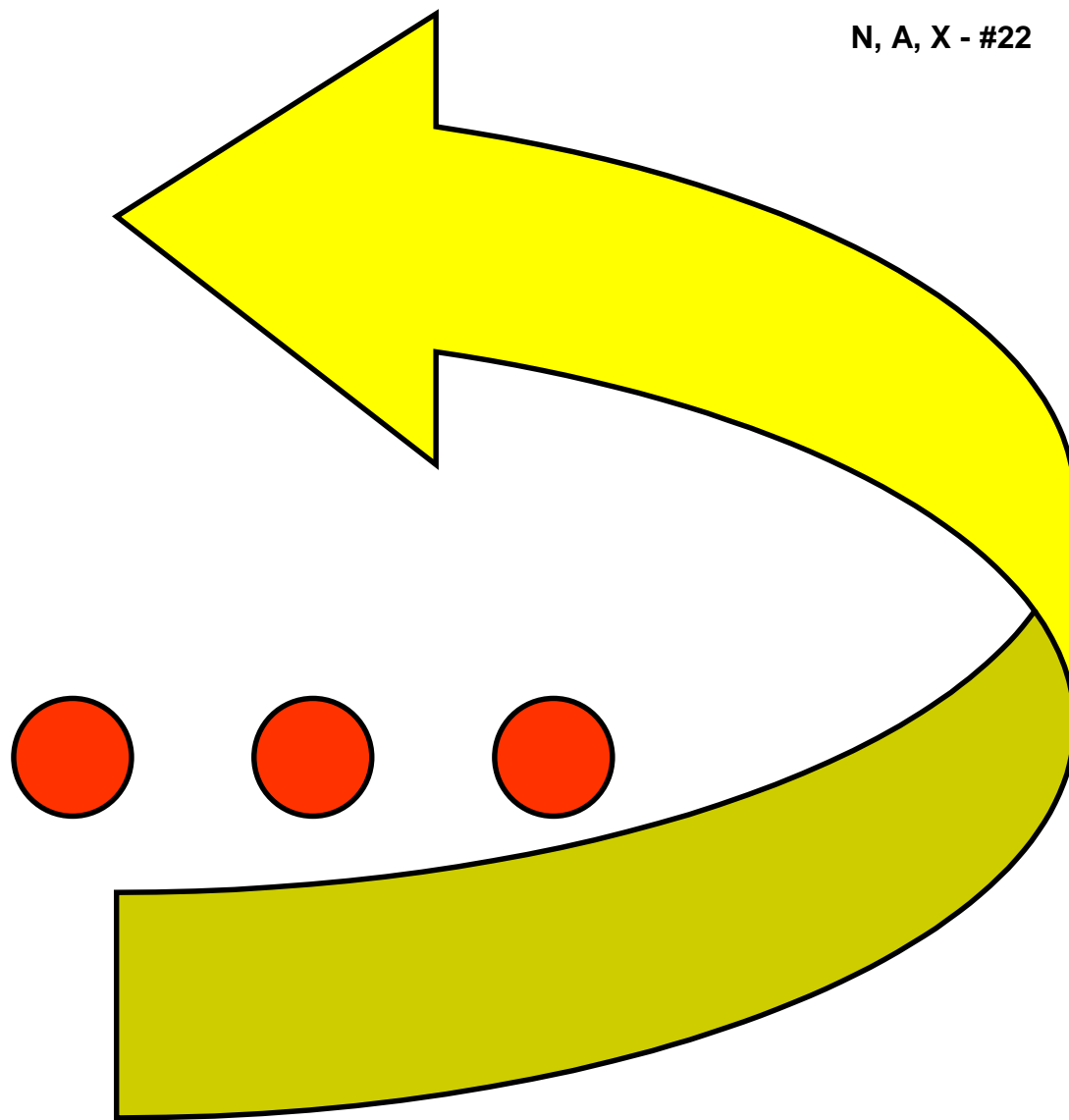




**Spiral
Right**

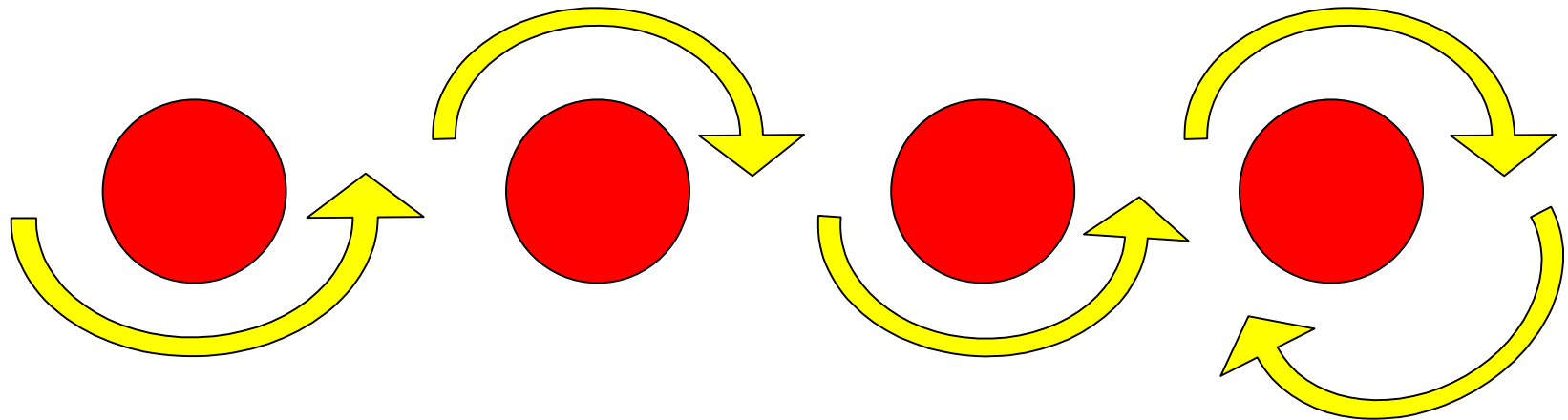
Dog Outside

**Spiral
Left**

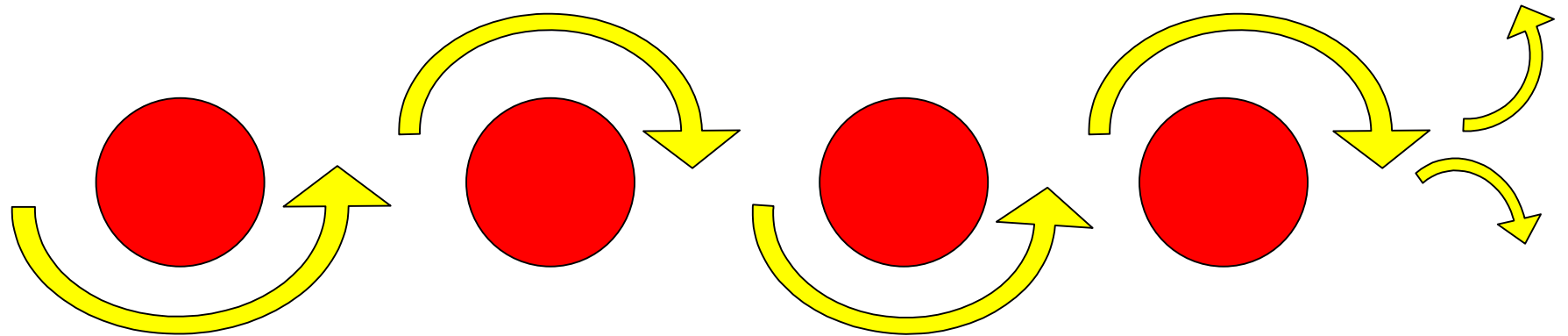


Dog Inside

Straight Figure 8 Weave Twice



Serpentine Weave Once





Halt

1 Step



Halt

2 Steps

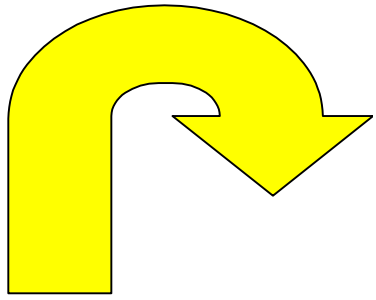


Halt

3 Steps



Halt



Call Front

1 Step Back



2 Steps Back



3 Steps Back





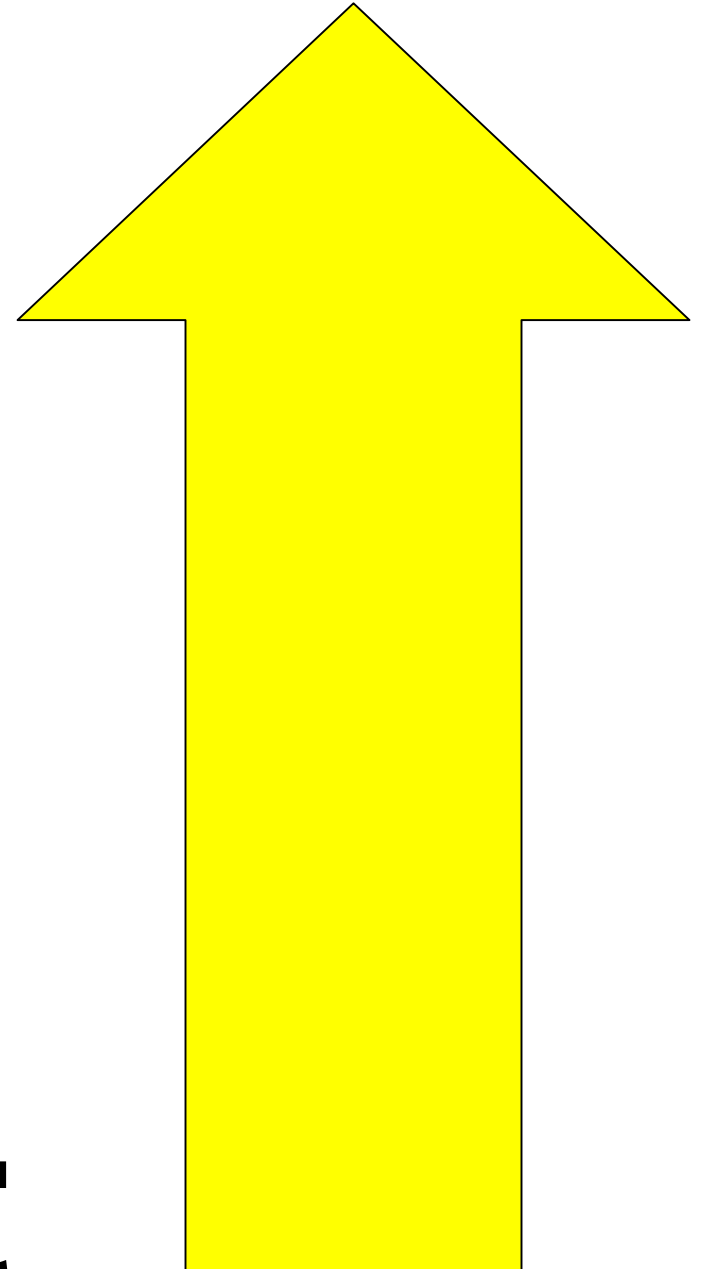
Moving Down



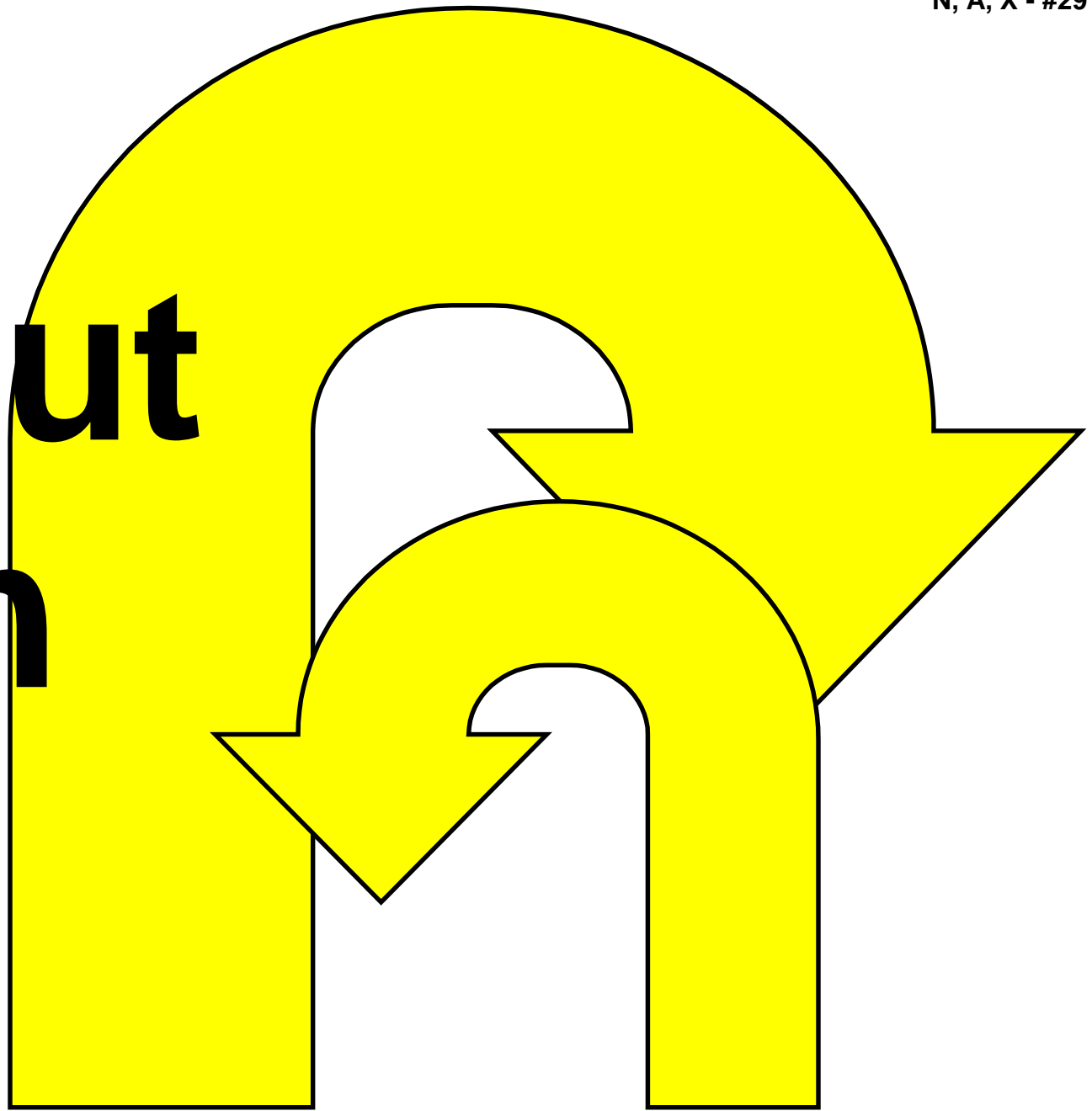
Fast

Forward

From Sit

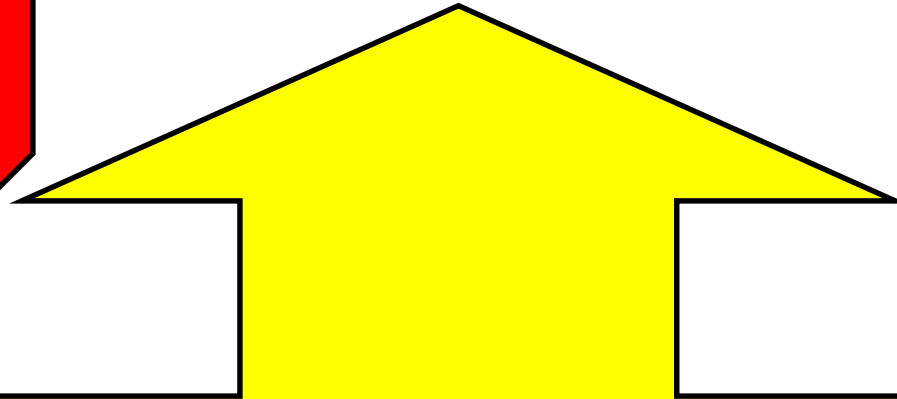


Left About Turn

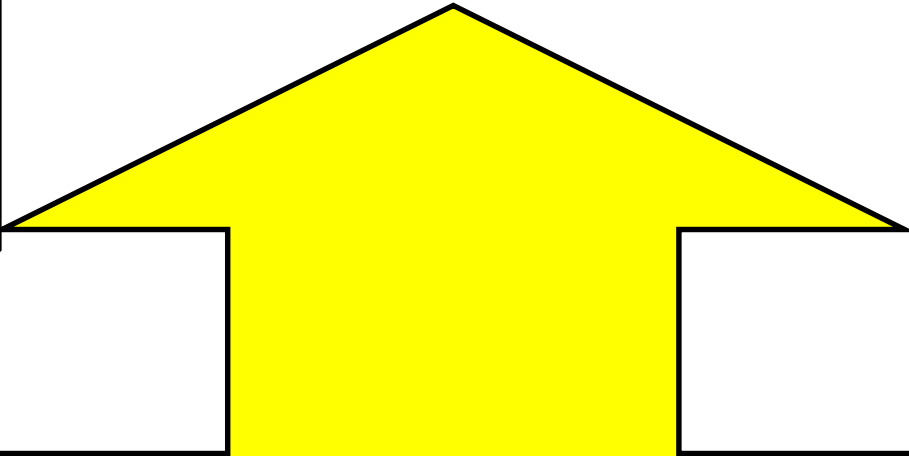


DOG

Handler



**Walk Around
Dog**

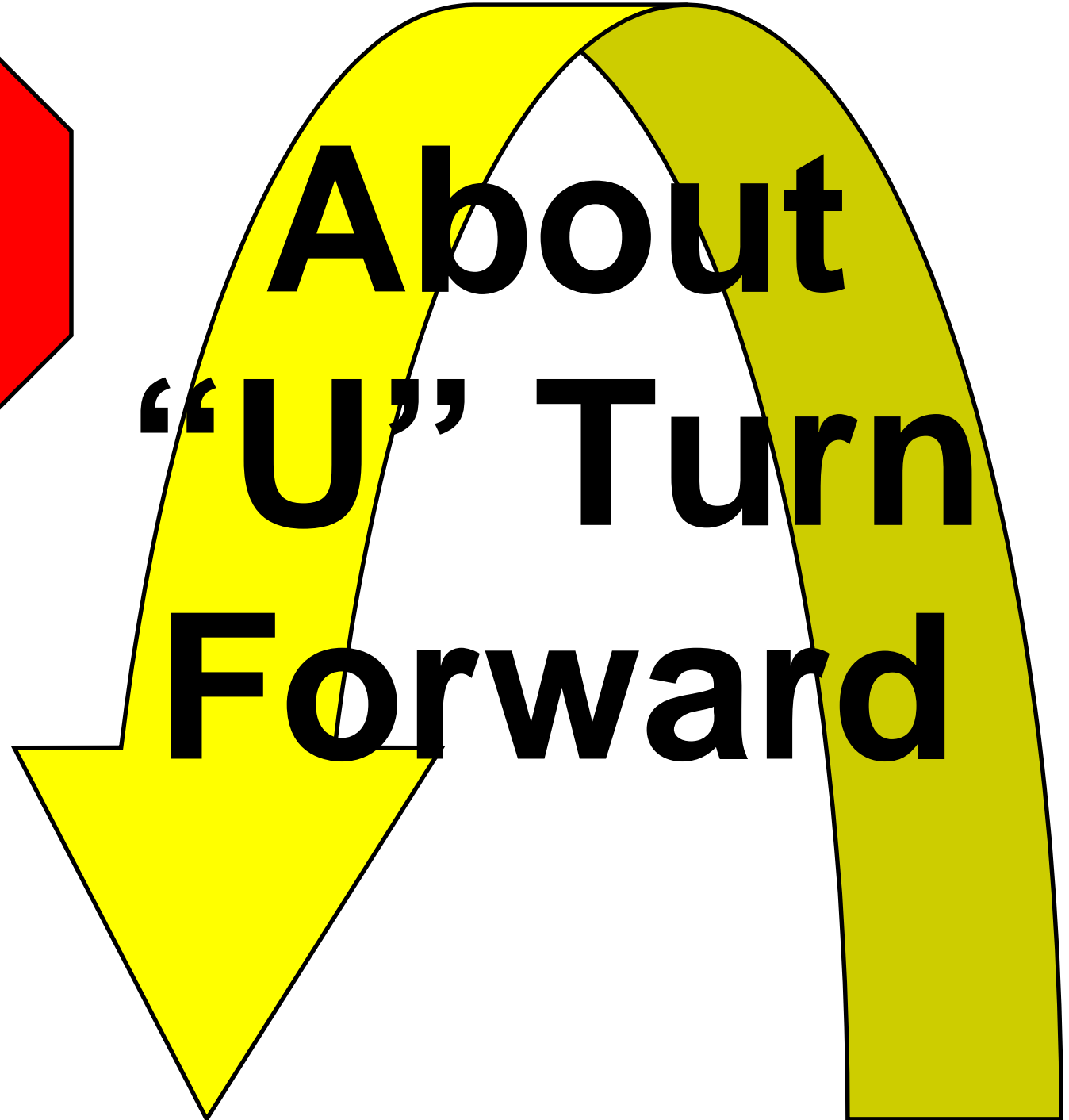


**Down
Walk Around
Dog**

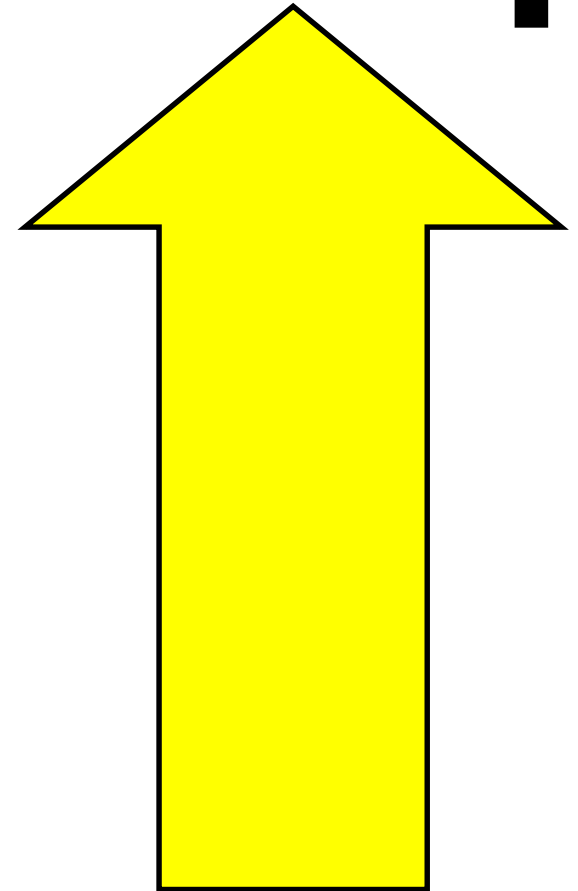
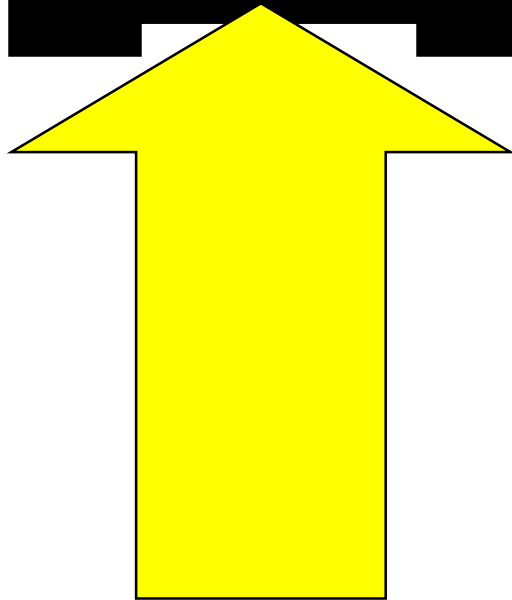


About
Turn Right
Forward





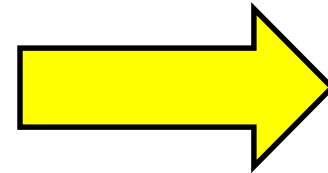
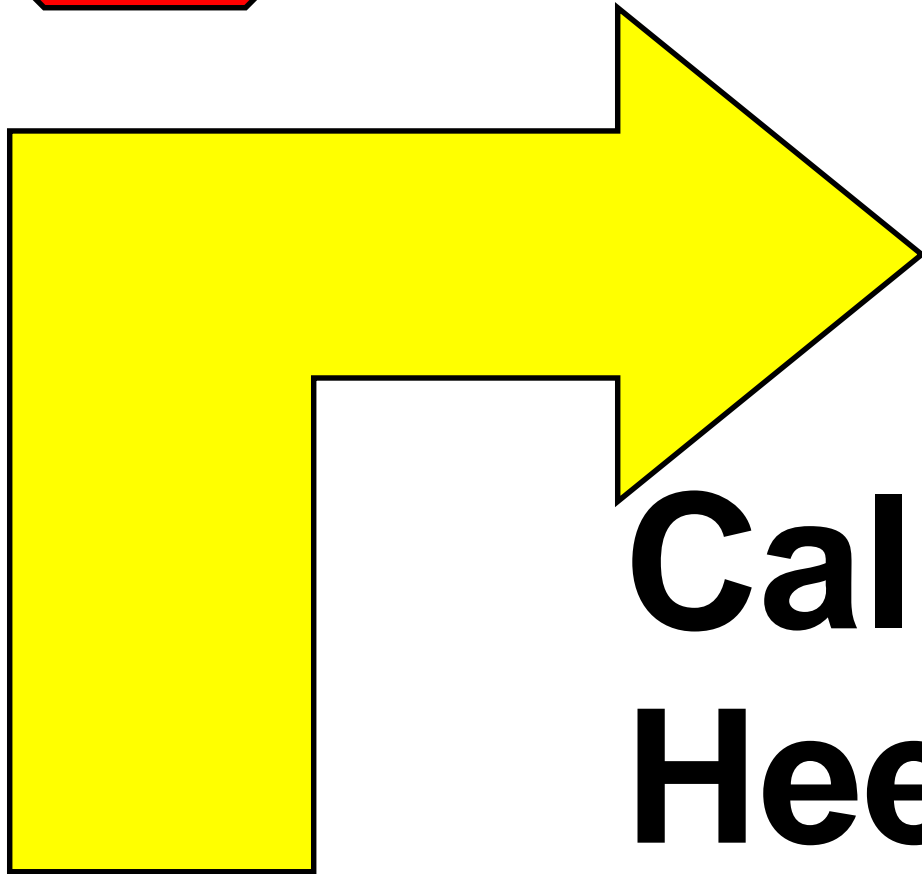
Send Over Jump



Handler Runs By

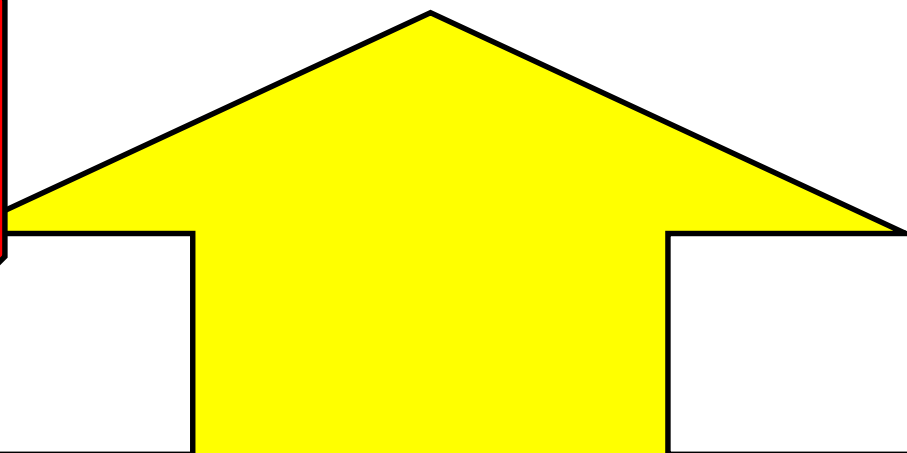


Turn Right
1 Step



Call to
Heel





Stand

Walk Around

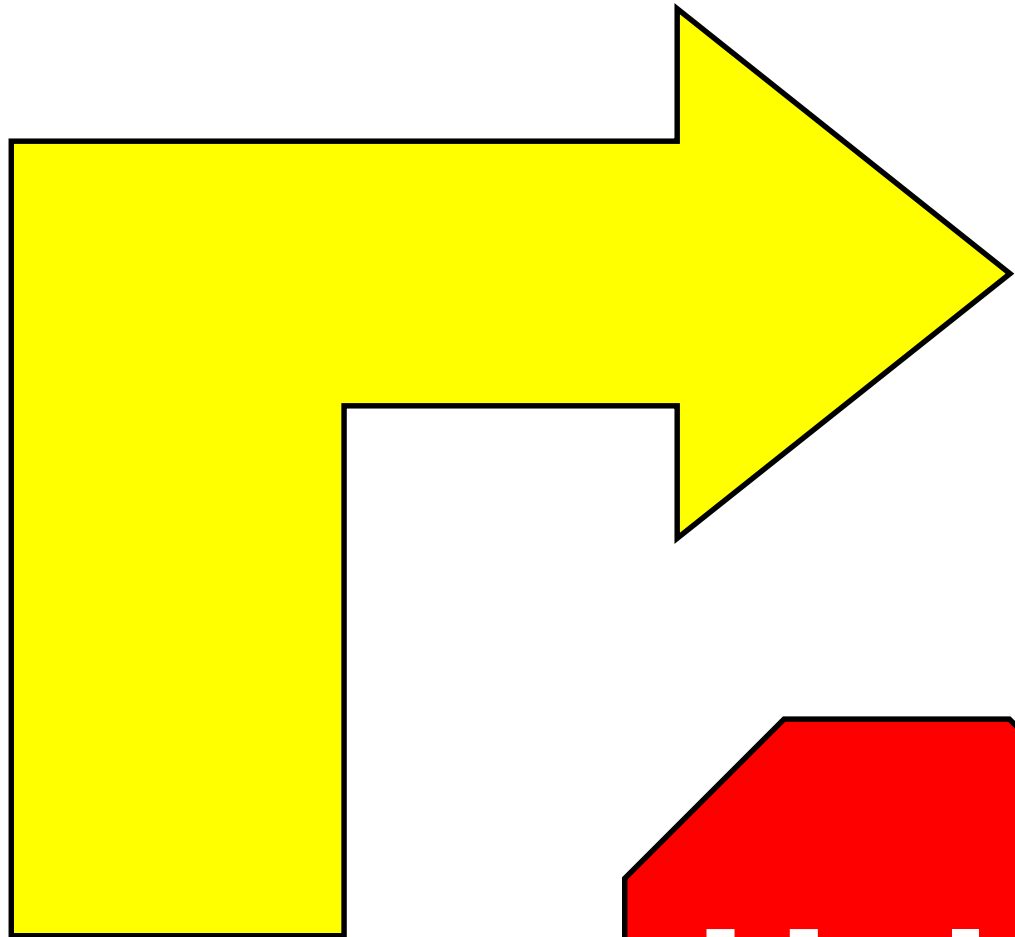
Dog

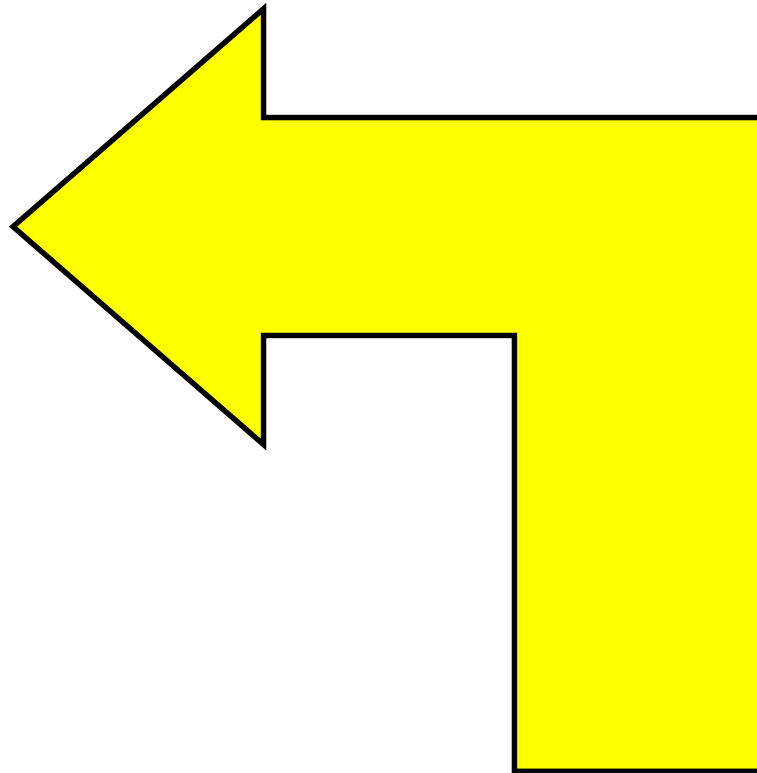


90°

Pivot

Right



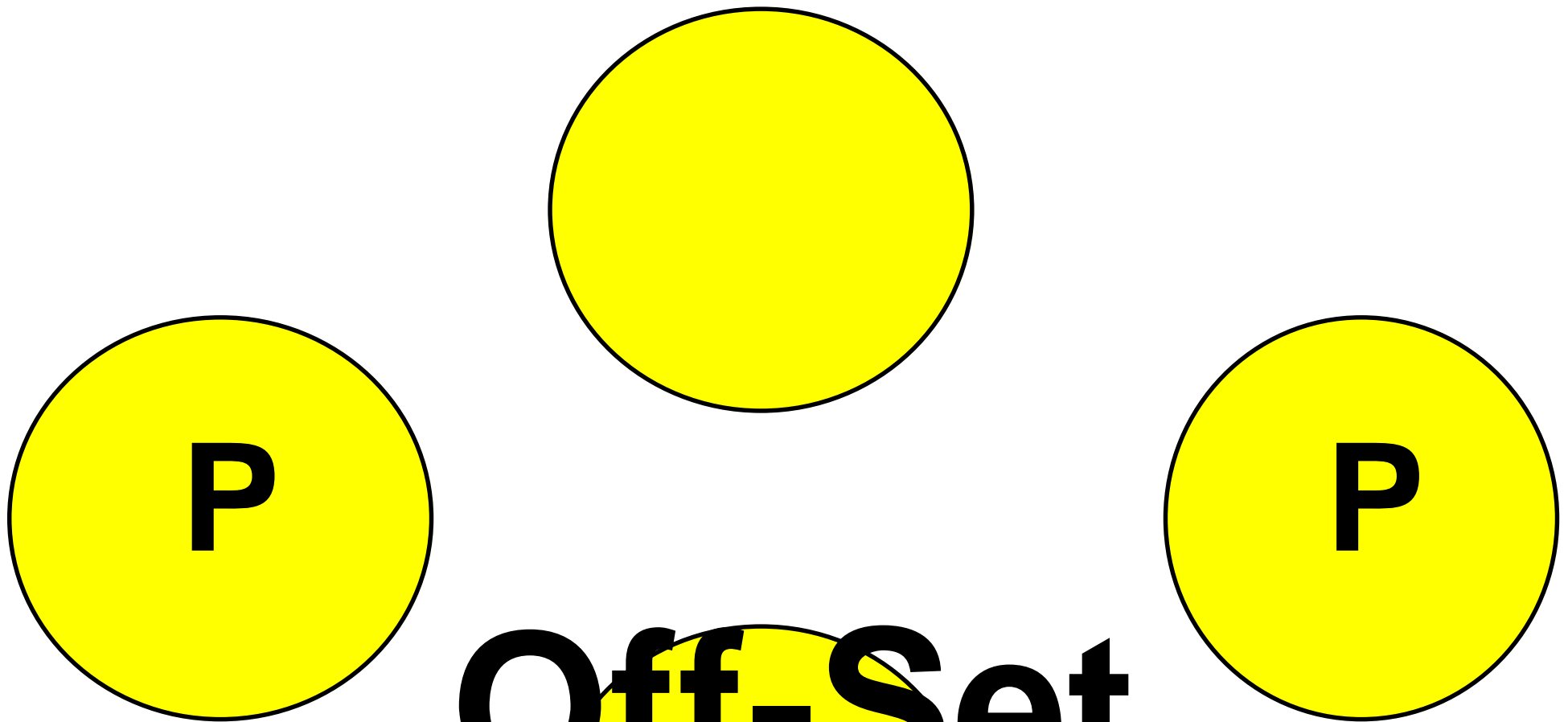


90°

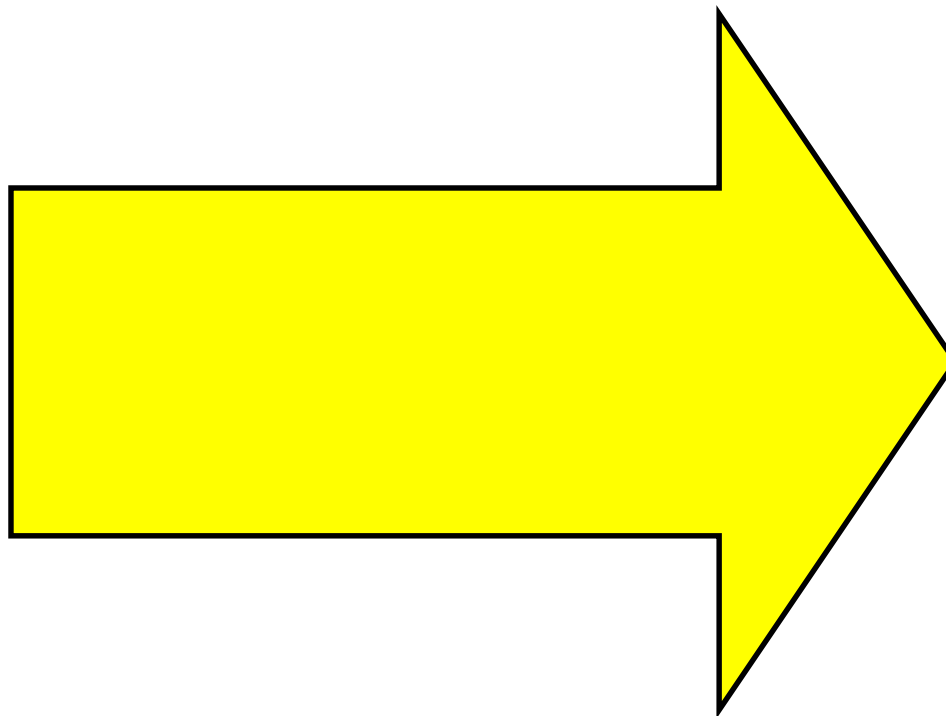
Pivot

Left



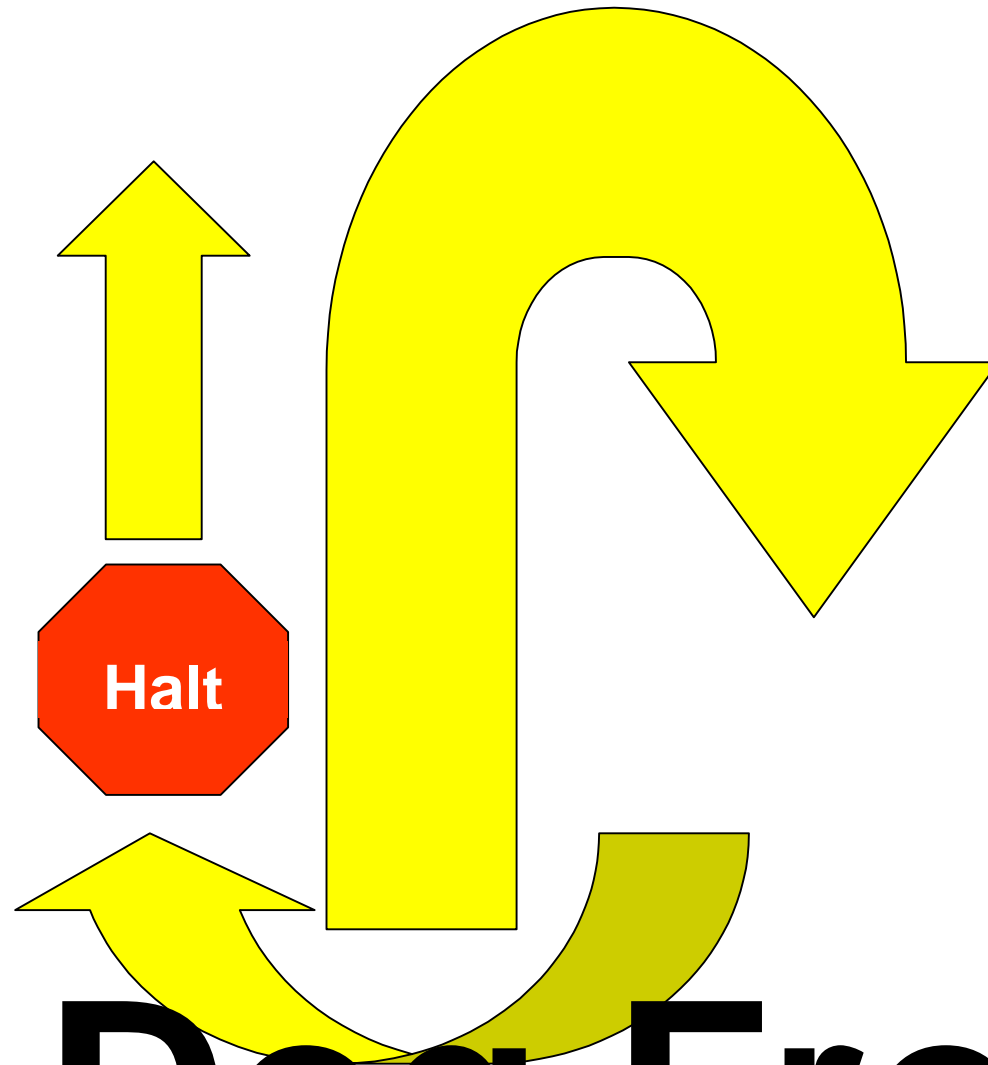


Off-Set
Figure 8

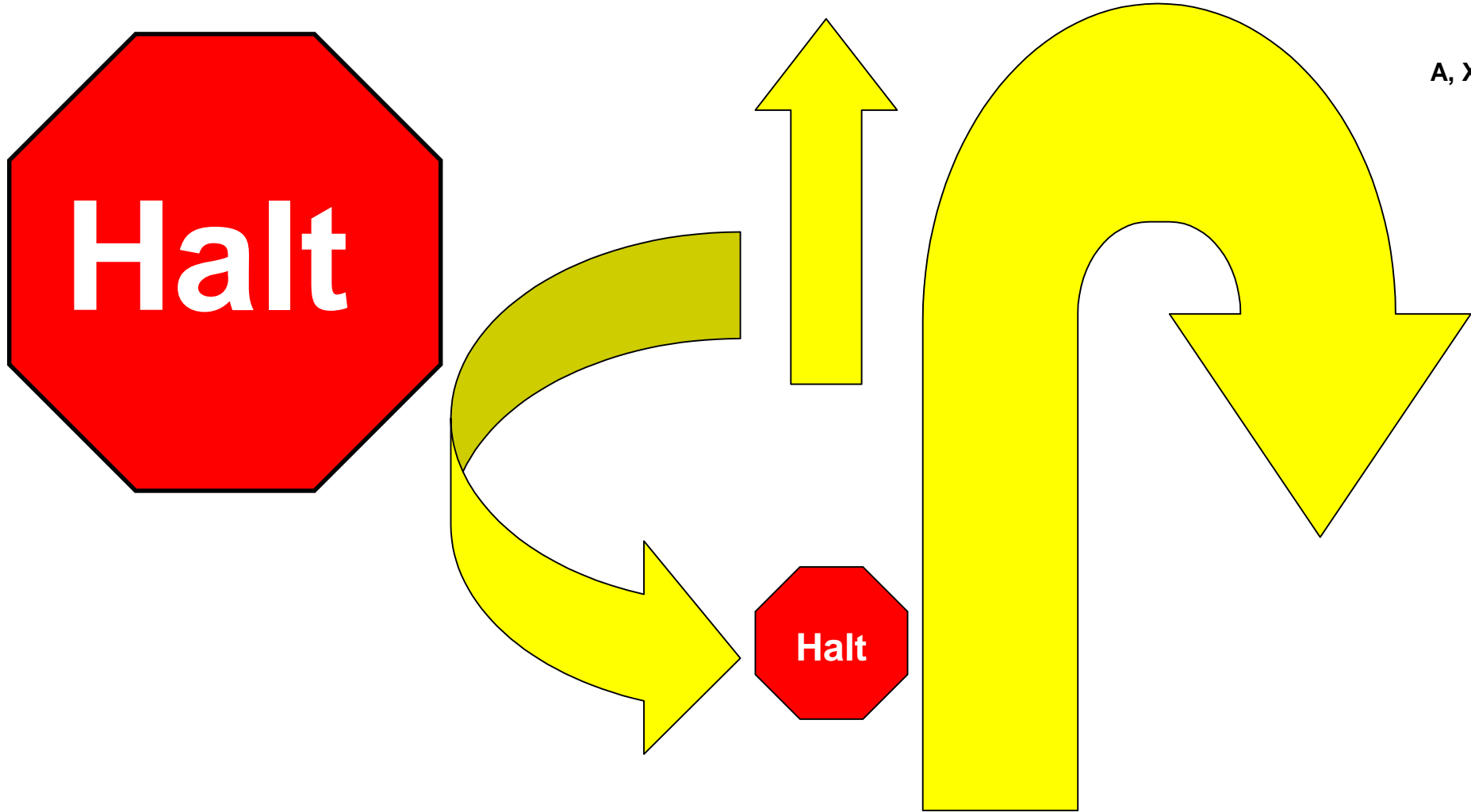


Side Step
Right





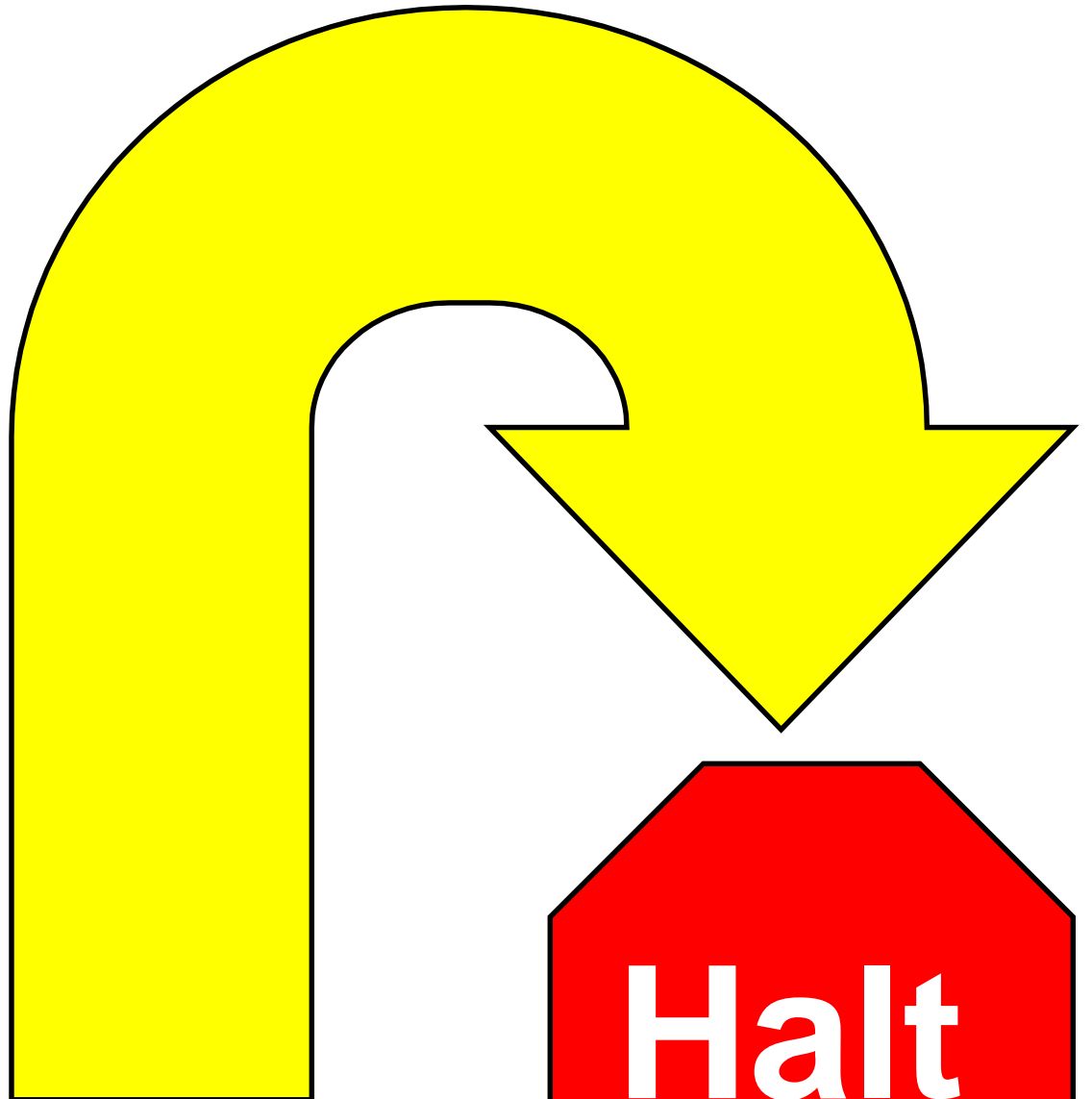
Call Dog Front
Finish Right



Call Dog Front
Finish Left



**180°
Pivot
Right**

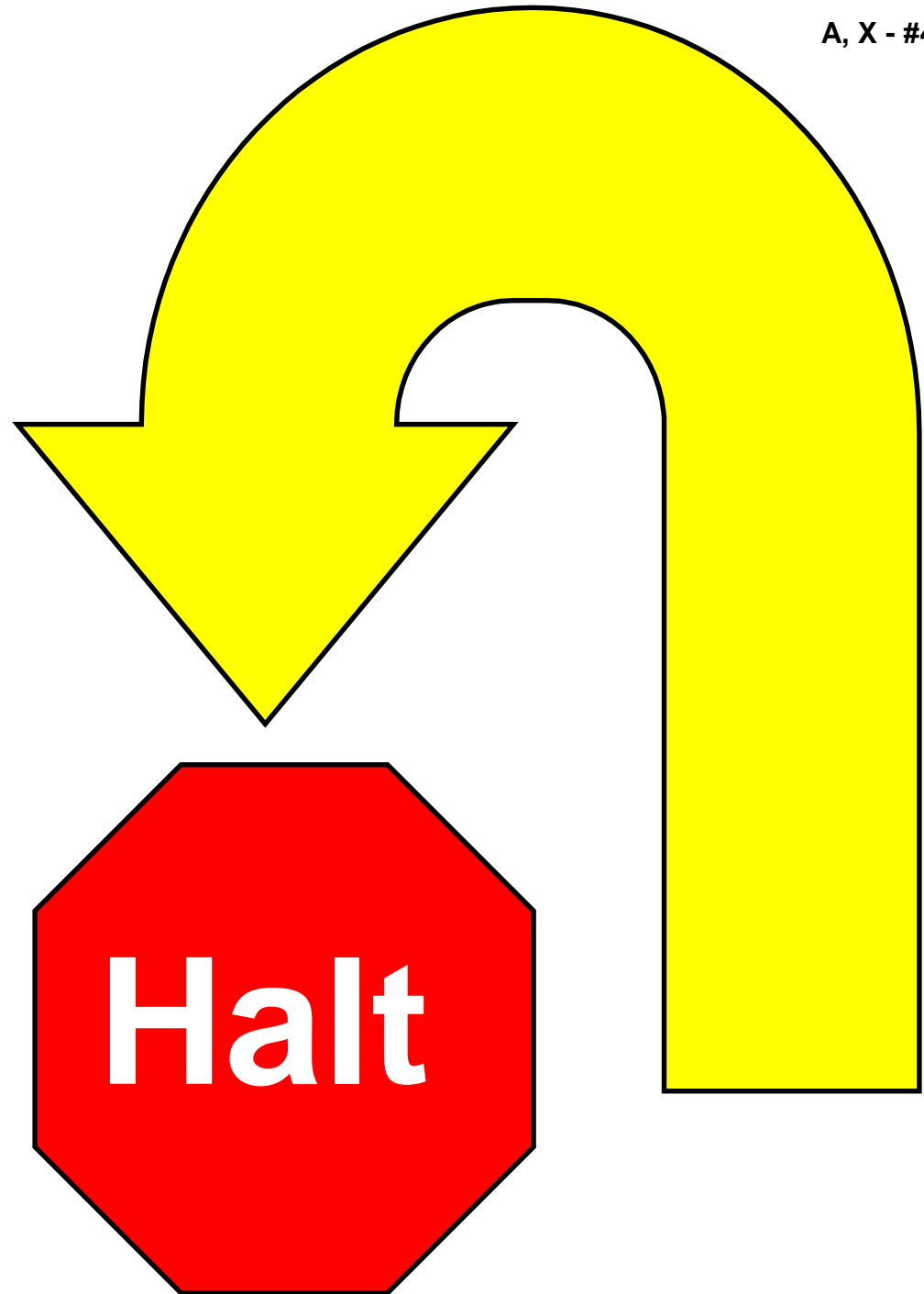


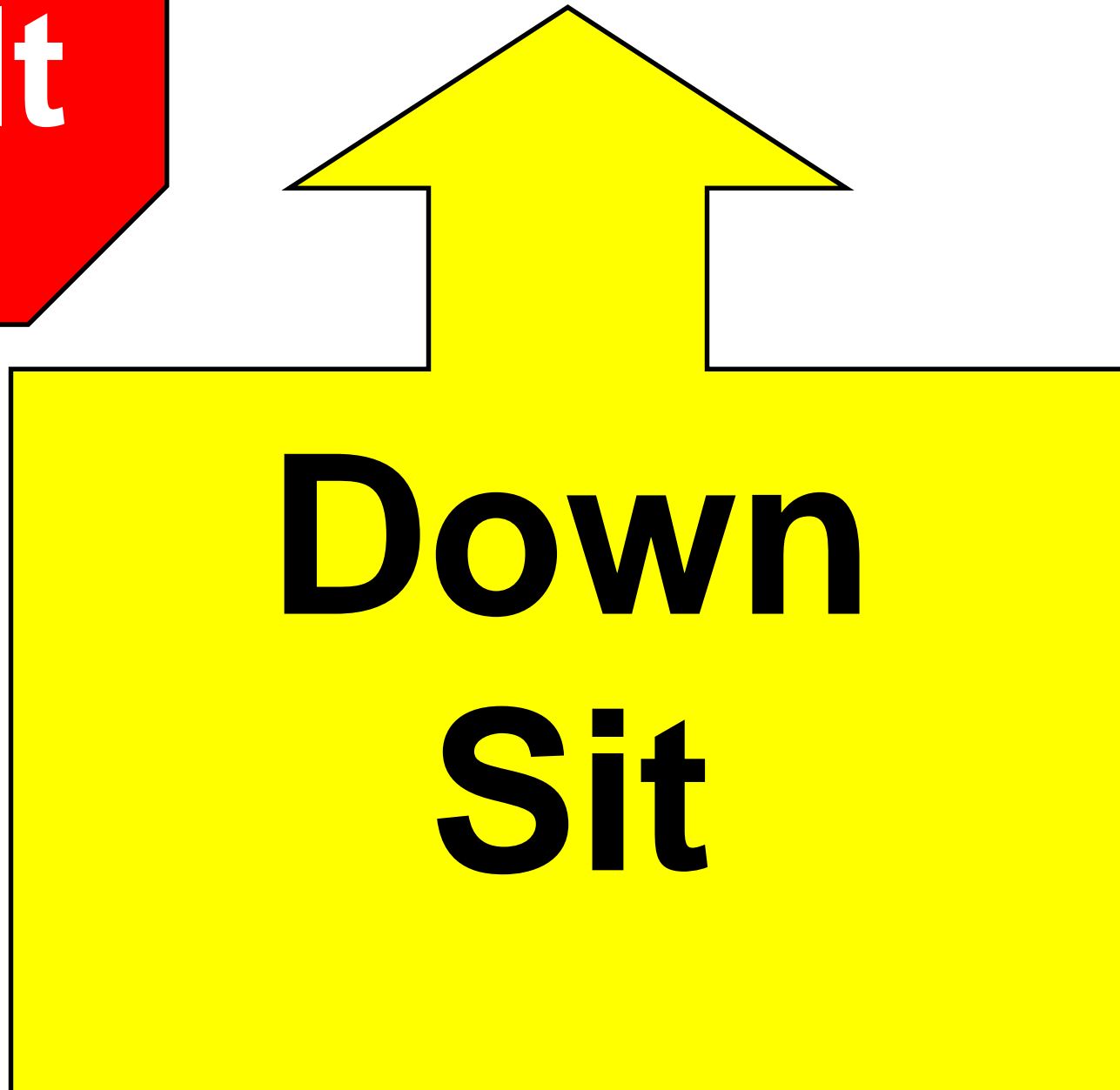


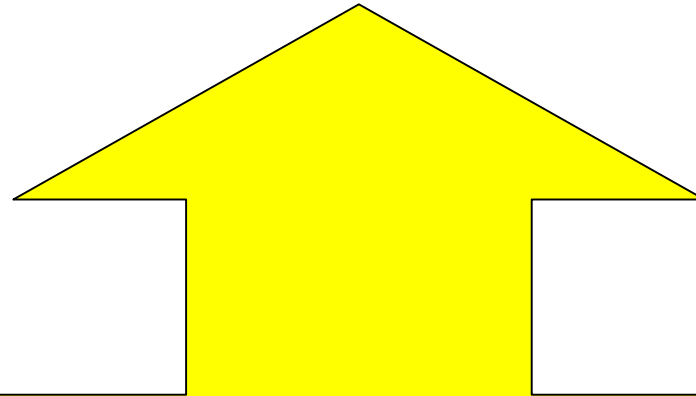
180°

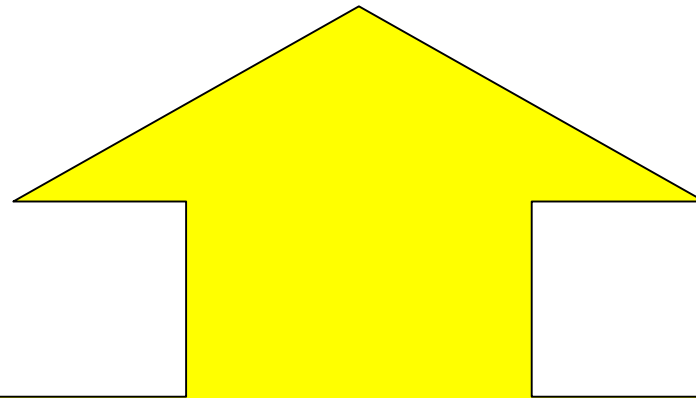
Pivot

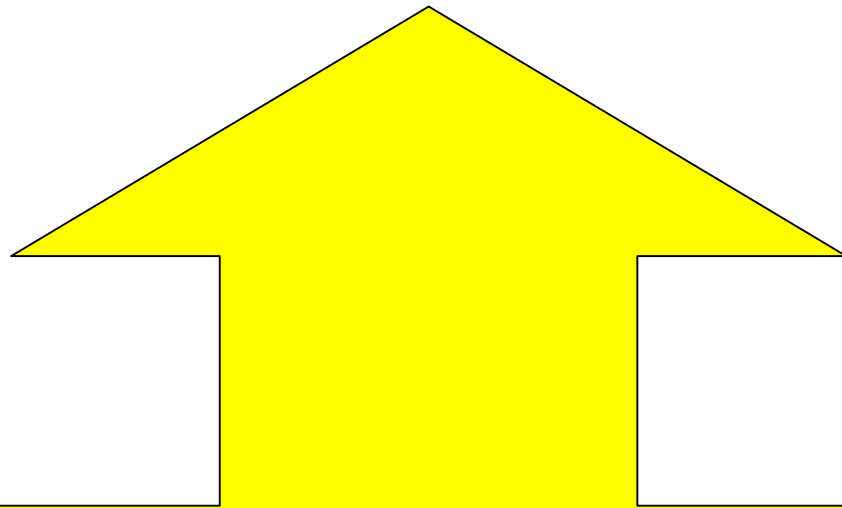
Left



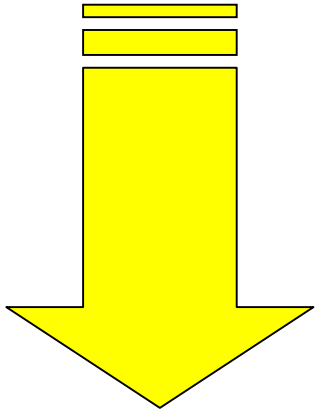




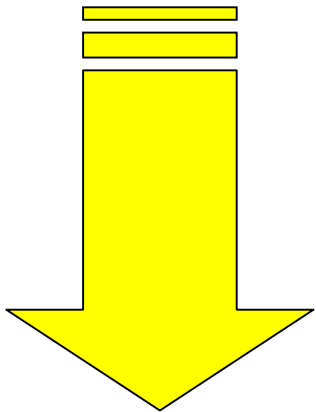




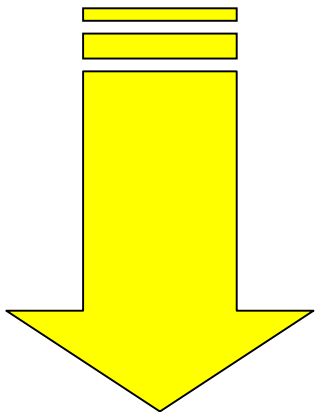
**Moving Stand
Walk Around
Dog**



Back Up 3



Steps Dog



Stays in

Position

Honor